Littlemore

Neighbourhood Development Plan

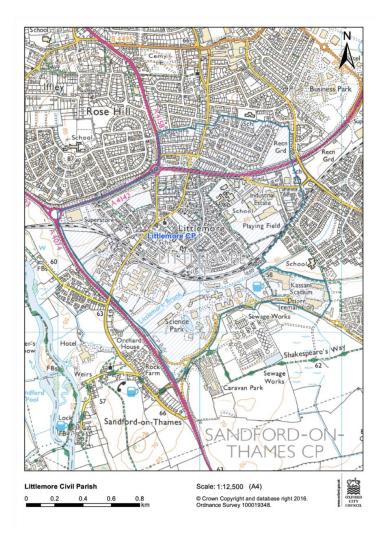
Information Statement

Referendum: 29th January 2026

A neighbourhood plan referendum will be held for the Littlemore Neighbourhood Development Plan 2025 - 2040 on 29th January 2026. The question asked in the referendum will be:

Do you want Oxford City Council to use the neighbourhood plan for Littlemore to help it decide planning applications in the neighbourhood area?

The referendum area and the area covered by the neighbourhood plan is the Littlemore Neighbourhood Area (see map below):



A person is entitled to vote in the Referendum on 29 January 2026 if:

- He or she is entitled to vote in a local government election in the referendum area; and
- His or her qualifying address for the election is in the Referendum area. A
 persons qualifying address is, in relation to a person registered in the register
 of electors, the address in respect of which he or she is entitled to be
 registered.

The Referendum expenses limit that will apply in relation to the Referendum is £2655.35.

The number of persons entitled to vote in the referendum by reference to which the limit has been calculated is **4972**.

The referendum will be conducted in accordance with procedures that are similar to those used at local government elections.

The specified documents are:

- Draft Littlemore Neighbourhood Development Plan
- Report of the independent examiner
- Summary of the representations submitted to the independent examiner
- Statement by the local planning authority that the draft plan meets the basic conditions (Decision statement)
- Statement that sets out general information on town and country planning including neighbourhood planning and the referendum (information for voters)

These documents can be viewed at:

https://www.oxford.gov.uk/neighbourhood-planning/littlemore-neighbourhood-plan

Oxford City Council main offices, between 9am and 4.30pm Monday to Friday

Oxford City Council main offices are located at Town Hall, St Aldate's, Oxford OX1 1BX.